

## HMG10P-T - CANopen®

Through hollow shaft / CANopen® / 13 bit ST / 16 bit MT

Speed switch, number of pulses and switching speed freely programmable

### Overview

- Interface CANopen®
- Magnetic sensing method
- Resolution: singleturn 13 bit, multiturn 16 bit
- Function display via LEDs
- Multiturn sensing with Energy Harvesting technology "MicroGen", without gear or battery
- Two-sided bearing system with hybrid bearings
- Special protection against corrosion CX (C5-M)



Picture similar

**HUBNER**  
BERLIN  
A Baumer Brand

**microGen**  
Energy Harvesting

### Technical data

#### Technical data - electrical ratings

Voltage supply	10...30 VDC
Short-circuit proof	Yes
Consumption w/o load	≤200 mA
Initializing time	≤ 500 ms after power on
Interface	CANopen®
Function	Multiturn
Transmission rate	10 ... 1000 kBaud
Device address	Rotary switches in bus connecting box
Steps per revolution	8192 / 13 bit
Number of revolutions	65536 / 16 bit
Additional outputs	Square-wave TTL/HTL, TTL/RS422
Sensing method	Magnetic
Interference immunity	EN 61000-6-2
Emitted interference	EN 61000-6-3
Programming interface	RS485 (≤600 m)
Programmable parameters	Bus system: see bus features Additional output (number of pulses), switch-off and switch-on speeds
Diagnostic function	Position or parameter error
Status indicator	DUO-LED (bus connecting box) 4 LEDs in device back side
Approval	CE UL approval / E217823 EAC

#### Technical data - electrical ratings (speed switch)

Switching accuracy	± 2 % (or 1 Digit)
Switching outputs	1 output (Open collector, solid state relay on request)

#### Technical data - electrical ratings (speed switch)

Output switching capacity	30 VDC; ≤100 mA
Switching delay time	≤20 ms
<b>Technical data - mechanical design</b>	
Size (flange)	ø105 mm
Shaft type	ø16...20 mm (through hollow shaft)
Flange	Support plate, 360° freely positionable
Protection EN 60529	IP 66/IP 67
Operating speed	≤6000 rpm
Range of switching speed	ns (off) = ±2...6000 rpm, factory setting 6000 rpm
Operating torque typ.	10 Ncm
Rotor moment of inertia	950 gcm <sup>2</sup>
Admitted shaft load	≤450 N axial ≤650 N radial
Material	Housing: aluminium alloy Shaft: stainless steel
Corrosion protection	IEC 60068-2-52 Salt mist for ambient conditions CX (C5-M) accord- ing to ISO 12944-2
Operating temperature	-40...+85 °C
Relative humidity	95 % non-condensing
Resistance	IEC 60068-2-6 Vibration 30 g, 10-2000 Hz IEC 60068-2-27 Shock 400 g, 1 ms
Weight approx.	2.2 kg (depending on version)
Connection	Bus connecting box Terminal box incremental

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### Optional

- Integrated speed switch programmable
- Additional output incremental programmable

# HMG10P-T - CANopen®

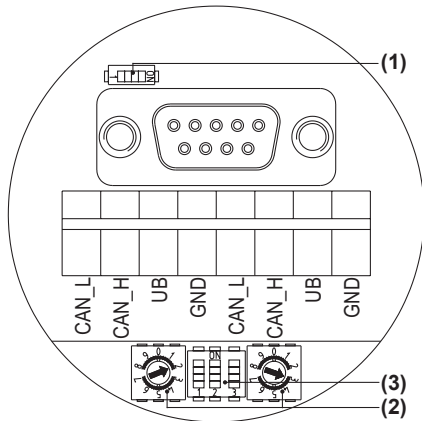
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## Terminal assignment

### CANopen - View A (see dimension)

View inside bus connecting box CANopen®

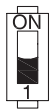


Terminals of the same significance are internally connected and identical in their functions. Max. load on the internal terminal connections UB-UB and GND-GND is 1 A each.

### Terminating resistor (1)

ON = Last user

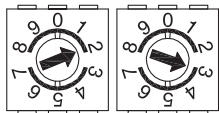
OFF = User x



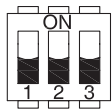
### User address (2)

Defined by rotary switch.

Example: User address 23



### CANopen - Transmission rate (3)



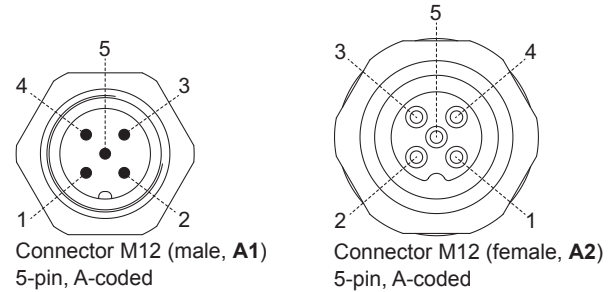
Transmission rate	Setting DIP switches		
	1	2	3
10 kBaud	OFF	OFF	OFF
20 kBaud	OFF	OFF	ON
50 kBaud*	OFF	ON	OFF
125 kBaud	OFF	ON	ON
250 kBaud	ON	OFF	OFF
500 kBaud	ON	OFF	ON
800 kBaud	ON	ON	OFF
1000 kBaud	ON	ON	ON

\* Factory setting

## Terminal assignment

### CANopen - View A1 and A2 (see dimension)

View into connector



Connector M12 (male, A1)  
5-pin, A-coded

Connector M12 (female, A2)  
5-pin, A-coded

Pin	Connection
1	GND
2	UB
3	GND
4	CAN_H
5	CAN_L

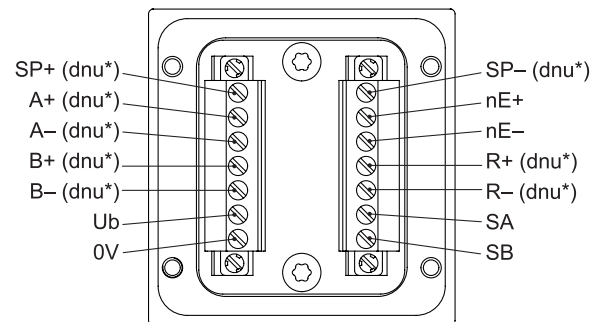
Terminals of the same significance are internally connected and identical in their functions. Max. load on the internal terminal connections GND-GND is 1 A each.

### View B (see dimension)

Connecting terminal terminal box

Programming interface / speed switch / additional output II (HTL, TTL)

\* Assignment depends on encoder version



## Terminal significance

### CANopen®

Connection	Description
GND	Ground for UB
UB	Voltage supply 10...30 VDC
CAN_H	CAN Bus signal (dominant HIGH)
CAN_L	CAN Bus signal (dominant LOW)

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Ub	Voltage supply
0V	Ground
A+	Output signal channel 1
A-	Output signal channel 1 inverted
B+	Output signal channel 2 (offset by 90° to channel 1)
B-	Output signal channel 2 inverted
R+	Zero pulse (reference signal)
R-	Zero pulse inverted
nE+	System OK+ / error output
nE-	System OK- / error output inverted
SP+	DSL_OUT1 / speed switch (open collector, solid state relay on request)
SP-	DSL_OUT2 / speed switch (0V, solid state relay on request)
SA	RS485+ / programming interface
SB	RS485- / programming interface
dnu	Do not use

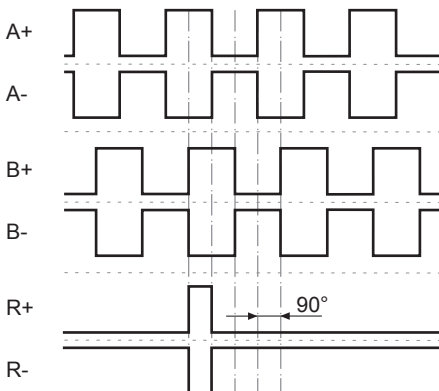
## CANopen® features

Bus protocol	CANopen®
Features	Device Class 2 CAN 2.0B
Device profile	CANopen® CiA DSP 406, V 3.0
Operating modes	<ul style="list-style-type: none"> <li>■ Polling mode (asynch, via SDO)</li> <li>■ Cyclic mode (asynch-cyclic)</li> <li>■ Synch mode (synch-cyclic)</li> <li>■ Acyclic mode (synch-acyclic)</li> </ul>
Diagnosis	The encoder supports the following error warnings: <ul style="list-style-type: none"> <li>■ Position error</li> </ul>
Factory setting	User address 00

## Output signals

### Additional output II (HTL/TTL)

At positive rotating direction (see dimension)



## Trigger level

### Incremental HTL/TTL

Electrically isolated:  
The output TTL/HTL (Vin = Vout) at the additional output II is electrically isolated and requires a separate power supply.

<b>Trigger level</b>	<b>TTL/RS422</b>
High / Low	≥2.5 V / ≤0.5 V

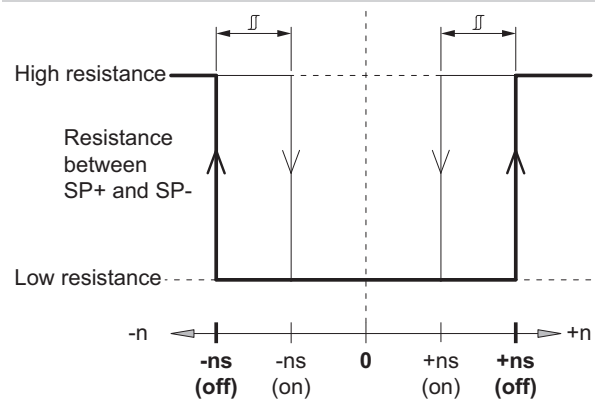
Transmission length	≤550 m @ 100 kHz
Output frequency	≤600 kHz

<b>Trigger level</b>	<b>TTL/HTL (Vin = Vout)</b>
High / Low	≥2.5 V / ≤0.5 V (TTL) ≥Ub -3 V / ≤1.5 V (HTL)

Transmission length	≤550 m @ 100 kHz (TTL) ≤350 m @ 100 kHz (HTL)
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Output frequency	≤600 kHz (TTL); ≤350 kHz (HTL)
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## Switching characteristics speed switch



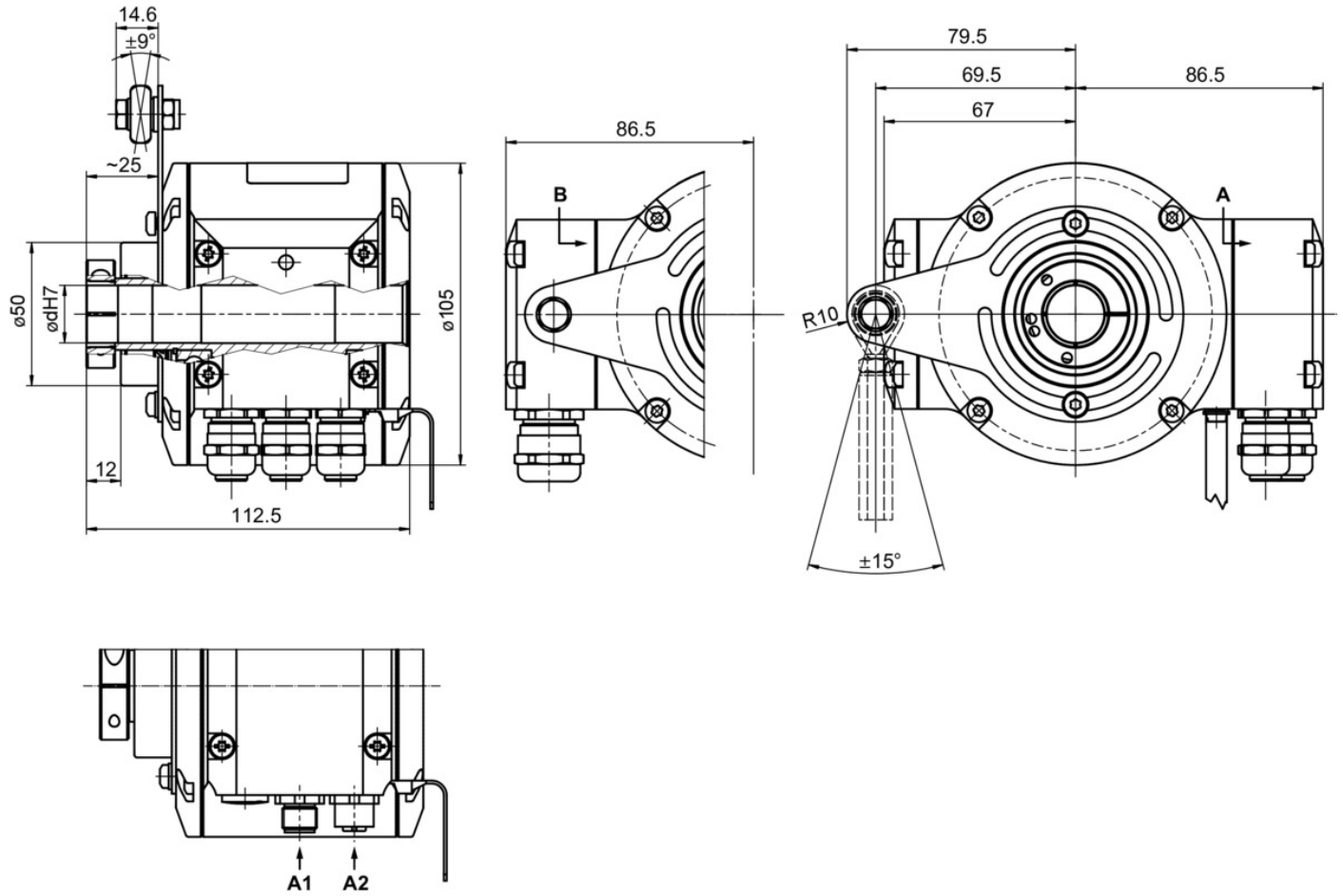
n	Speed
+ns (off)	Switch-off speed at shaft rotation in positive rotating direction (see dimension).
-ns (off)	Switch-off speed at shaft rotation in negative rotating direction (see dimension).
	Switching hysteresis $\Delta$ : 10...100 % (factory setting = 10 % min. 1 Digit)
+ns (on)	Switch-on speed at shaft rotation in positive rotating direction (see dimension).
-ns (on)	Switch-on speed at shaft rotation in negative rotating direction (see dimension).

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## Dimensions



Through hollow shaft with terminal box

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**Ordering reference**

	HMG10P	#	-	T	H	#	.	#	#	C6	3	.	#	0	0	#	A
<b>Product</b>	HMG10P																
Absolute encoder	HMG10P																
<b>Digital speed switch</b>																	
Without	-																
With	D																
<b>Shaft type</b>																	
Through hollow shaft	T																
<b>Flange (Hollow shaft)</b>																	
Support (Support plate) for torque arm, hybrid bearings	H																
<b>Protection class</b>																	
IP 66 and IP 67, optimized for dusty, abrasive environment	D																
IP 66 and IP 67, optimized for oily, wet environment	L																
<b>Through hollow shaft</b>																	
Ø16 mm, clamping ring, A end	C																
Ø20 mm, clamping ring, A end	F																
Ø16 mm, keyway	P																
<b>Connection</b>																	
Bus connecting box with 3 cable glands M16, radial + terminal box with 1 cable gland M20, radial	F																
Bus connecting box with 2 connectors M12, radial + terminal box with 1 cable gland M20, radial	Z																
<b>Supply voltage (field bus)</b>																	
10...30 VDC, CANopen (DS 406)	C6																
<b>Resolution singleturn position</b>																	
13 Bit	3																
<b>Resolution multiturn position</b>																	
No multiturn signal	0																
16 Bit	6																
<b>Resolution speed</b>																	
No speed signal	0																
<b>Resolution supplement I</b>																	
No additional output I	0																
<b>Resolution supplement II</b>																	
No additional output II	0																
1024 ppr TTL/HTL push-pull (Vin=Vout), 6 channels, electrically isolated	5																
1024 ppr TTL (RS422), 6 channels	6																
<b>Operating temperature</b>																	
-40...+85 °C	A																

- (1) Switching speed 6000 rpm / factory setting, programmable  
 (2) Factory setting, programmable

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### Accessories

#### Mounting accessories

11043628	Torque arm M6, length 67...70 mm
11004078	Torque arm M6, length 120...130 mm ( $\geq 71$ mm)
11002915	Torque arm M6, length 425...460 mm ( $\geq 131$ mm)
11054917	Torque arm M6 insulated, length 67...70 mm
11072795	Torque arm M6 insulated, length 120...130 mm ( $\geq 71$ mm)
11082677	Torque arm M6 insulated, length 425...460 mm ( $\geq 131$ mm)
11077197	Mounting kit for torque arm size M6 and earthing strap
11077087	Mounting and dismounting set

#### Connectors and cables

11191145	Programming cable for the HMG10P/PMG10P bus interfaces series
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#### Programming accessories

11190106	Z-PA.SDL.1 - WLAN-Adapter
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